

"Proof" Thm 2.2

Ass: H nonuniform learnable with A , $m_{\epsilon}^{NUL} \Rightarrow H = \bigcup_{\epsilon > 0} H_{\epsilon}$, each H_{ϵ} is agnostic PAC learnable

Recall Corollary 6.4 (NBE)
 \bar{X} domain, $V \subset \mathcal{H}$, $V \cap \bar{X} \neq \emptyset$ ($\Rightarrow \exists C \in \bar{X}, |C| \geq 2n, H$ shatters C)
 \Rightarrow Learning algorithms A , $\exists D: \exists \epsilon > 0: L_D(h) \leq \epsilon$
 with prob $\geq \frac{1}{2}$ over $S \sim \mathcal{D}^n$; $L_D(A(S)) \geq \epsilon$

[Holds also for A which learn one on $H \geq \bar{X}$]

Proof: $H_{\epsilon} = \{h \in \mathcal{H}: m_{\epsilon}^{NUL}(h) \leq \epsilon\}$

\bar{D} realizable wrt \mathcal{H} , $S \sim \bar{D}^n$
 $\forall h \in H_{\epsilon}: L_D(A(S)) \leq L_D(h) + \epsilon$
 $\Rightarrow \underbrace{L_D(A(S))}_{\leq \epsilon} \leq \underbrace{L_D(h)}_{\leq \epsilon} + \epsilon = 2\epsilon$ $L_D(A(S)) \leq 2\epsilon$

Assume $V \cap \bar{X} \neq \emptyset$

So apply Cor 6.4 (Learning alg A , D with realiz. wrt \mathcal{H} s.t. with prob $\geq 1/2$ over $S \sim \bar{D}^n$ $L_D(A(S)) \geq \epsilon$)

\downarrow It should hold for A , as well
 $\Rightarrow V \cap \bar{X} = \emptyset$
 $\Rightarrow H_{\epsilon}$ is agnostic PAC-learnable

Recall SEM: argmin $L_S(h) + \epsilon_{\text{err}}(m, w, \epsilon, \mathcal{H}, S)$
 $n(h) = \min_{w \in \Delta} \sum_{i=1}^m w_i \log \frac{1}{h(x_i)}$
 $\epsilon_{\text{err}}(m, w, \epsilon, \mathcal{H}, S) = \min_{h \in \mathcal{H}} \sum_{i=1}^m w_i \log \frac{1}{h(x_i)}$

MDL and Occam's Razor (as a special case of SEM)

H countable $\Rightarrow \bigcup_{i \in \mathbb{N}} \{h_i\} = H$
 $m_{\text{acc}}^{\text{true}}(h) \leq \log \left(\frac{1}{\epsilon} \sum_{i \in \mathbb{N}} \frac{1}{2^i} \right) = \log \left(\frac{2}{\epsilon} \right)$
 $\epsilon_{\text{err}}(m, \delta) = \sqrt{\frac{\log(2/\delta)}{2m}}$, $n(h) = m$

SRM becomes argmin $L_S(h) + \sqrt{\frac{\log(1/n(h)) \log(1/\delta)}{2m}}$
 $= \dots + \sqrt{\frac{\log(1/n(h)) \log(1/\delta)}{2m}}$

Want to use a w based on a description language:

Σ : finite alphabet (e.g. {0,1})
 Σ^* : all finite strings over Σ
 $d: H \rightarrow \Sigma^*$ description language

Focus on prefix-free languages:

$\forall h, h' \in H: d(h)$ is prefix of $d(h')$

Kraft inequality: $S \subseteq \{0,1\}^*$ prefix-free

$$\sum_{s \in S} \frac{1}{2^{|s|}} \leq 1$$

Proof: Draw 0,1 uniformly at random (don't stop if it equals string)

$$\sum_{s \in S} \frac{1}{2^{|s|}} = P(S) \leq 1$$

We can use $d(h)$ as a weight $w(h) = \frac{1}{2^{|d(h)|}}$

MDL: argmin $L_S(h) + \sqrt{\frac{(|d(h)| + \ln(2/\delta) - 1)}{2m}}$

Tradeoff between emp. risk and "complexity" of describing h

Occam's Razor:

"A short explanation tends to be more valid than a long one"

Consistency

Algorithm A is consistent wrt. \mathcal{H} and \mathcal{P} (set of distributions) if: $\exists m \text{ con } (0, \epsilon)^m \times \mathcal{H} \times \mathcal{P} \rightarrow \mathcal{H}$ s.t.

$\forall \epsilon, \forall h \in \mathcal{H}, \forall D \in \mathcal{P}: L_D(A(S)) \leq L_D(h) + \epsilon$

Example: Memorizer is consistent

Given a test instance x , Memorizer returns the majority of the labels of instances in the sample, which are equal to x . (just predict the majority of all labels if there is no x)

\Rightarrow This notion is to weak to capture "learning"

Comparison

	Bounds on true error by the emp. risk	How many emp. con. needed to be as best as any hyp. in \mathcal{H} (in terms of)	Evade prior knowledge
(PAC)	✓	✓	✓ (capacity $\frac{1}{\epsilon \ln 2}$)
Nonuniform	✓ (with γ)	✓ depends on the best h in \mathcal{H}	✓ (weights)
Consistent	✗	✗	✗

Runtime of Algorithms

Input-size?

e.g. sample size is a bad idea.

\rightarrow depend on ϵ and δ

Computational Complexity for Learning Algorithms

A solves a learning task $(\mathcal{Z}, \mathcal{H}, \nu)$

in time $O(f(\epsilon, \delta))$, if:

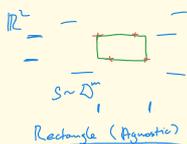
- A terminates in $O(f(\epsilon, \delta))$ time.
- output of A should applicable to (new) instances in $O(f(\epsilon, \delta))$ time.
- ag. PAC learn $(\mathcal{Z}, \mathcal{H}, \nu)$

A solves a sequence of learning problems

$(\mathcal{Z}_n, \mathcal{H}_n, \nu_n)_{n \in \mathbb{N}}$ in $O(f_n(\epsilon, \delta))$ if:

for each fixed n , A solves $(\mathcal{Z}_n, \mathcal{H}_n, \nu_n)$ in time $O(f_n(\epsilon, \delta))$ (efficient if $f_n = O(\frac{1}{\epsilon^c})$)

Example: Rectangles (learnable) in \mathbb{R}^2



For each dim: find min and max in $O(m)$ time
 Total time $O(m^2)$
 $= O(n \cdot \log(1/\delta))$

It's NP-hard to compute the ERM-rectangle. One can learn it in $O(m \log(1/\delta))$.